

IN THE CLAIMS:

1. (Currently Amended) A laser welding device for welding one or more said components (7), the device comprising:

one or more said laser welding heads (2), ~~characterized in that~~ said laser welding device (1) has:

5 one or more said moving means (8) for said components (7) for a relative movement of said components in relation to said laser welding head (2), which is designed as said laser welding heads including a remote laser ~~and~~ is arranged at a spaced location from said component (7).

2. (Currently Amended) A laser welding device in accordance with claim 1, ~~characterized in that~~ wherein said moving means (8) are designed as a said comprises a component conveyor (9).

3. (Currently Amended) A laser welding device in accordance with claim 1, ~~characterized in that~~ wherein said moving means (8) are designed as a said comprises a multiaxial robot (10).

4. (Currently Amended) A laser welding device in accordance with claim 1, ~~2 or 3~~, ~~characterized in that~~ wherein said laser welding head (2) is arranged stationarily.

5. (Currently Amended) A laser welding device in accordance with claim 1, ~~2 or 3~~, characterized in that wherein said laser welding head (2) is arranged nonstationarily by means of a said moving unit (11).

6. (Currently Amended) A laser welding device in accordance with ~~one of the above claims~~ claim 1, characterized in that wherein said laser welding head (2) has one or more scanner heads for the controllable deflection of said laser beam (4).

7. (Currently Amended) A laser welding device in accordance with ~~one of the above claims~~ claim 1, characterized in that wherein said moving means (8) for said components (7) is controlled according to the focal distance.

8. (Currently Amended) A laser welding device in accordance with ~~one of the above claims~~ claim 1, characterized in that wherein said laser welding head (2) has a focal distance of approx. 200 mm to 400 mm.

9. (Currently Amended) A laser welding device in accordance with ~~one of the above claims~~ claim 1, characterized in that wherein a plurality of said laser welding heads (2) are connected to a said common external laser beam source (3) by means of a said controllable beam switch (6) and said laser beam guides (5).

10. (Currently Amended) A process for the laser welding of one or more said components (7) by means of one or more said laser welding heads (2), ~~characterized in that~~  
said- the process comprising the steps of: guiding the components (7) are guided and moved  
during welding using by one or more said moving means (8) by a preferably for a multiaxial  
relative movement of the components in relation to said laser welding head (2), ~~which is~~  
~~designed as~~ and providing the one or more welding heads with a remote laser and is arranged  
at a spaced location from said the component (7).  
5

11. A process for laser welding in accordance with claim 10, ~~characterized in that~~  
wherein said components (7) are moved by one or more said multiaxial robots (10).

12. (New) A laser welding device for welding components, the device comprising:  
laser welding heads;  
a moving means for providing a relative movement of each of said components in  
relation to one or more of said laser welding head; and  
5 a laser beam source and laser beam transmission element, said laser beam source being  
at a remote location from said welding head and arranged at a spaced location from said  
component, said laser beam transmission element transmitting the laser beam to the welding  
head.

13. (New) A laser welding device in accordance with claim 12 wherein said moving

means comprises a component conveyor.

14. (New) A laser welding device in accordance with claim 12, wherein said moving means comprises a multiaxial robot.

15. (New) A laser welding device in accordance with claim 12, wherein said laser welding head is arranged stationarily.

16. (New) A laser welding device in accordance with claim 12, wherein said laser welding head is arranged nonstationarily by means of a moving unit.

17. (New) A laser welding device in accordance with claim 12, wherein said laser welding head has one or more scanner heads for the controllable deflection of said laser beam.

18. (New) A laser welding device in accordance with claim 12, wherein said moving means for said components is controlled according to the focal distance of the welding head.

19. (New) A laser welding device in accordance with claim 12, wherein said laser welding head has a focal distance of approx. 200 mm to 400 mm.

20. (New) A laser welding device in accordance with claim 19, wherein said laser beam

transmission element is a plurality of said laser welding heads are connected to said laser beam source as a common external laser beam source by a controllable beam switch and via laser beam guides.